Final Project Group Logistics

- You need to have finalized your groups of 3-4 for the final project.

- They do not have to be in your section.
- They do not have to be in the same course code.
- Place your information in the signup sheet if you haven’t!
  - Email Toki and myself if you haven’t received your Genbu login details yet!
Principles of Robot Autonomy I

Section 6: Continuing Section 5 and rosbags!
Aims

• Continue any work you haven’t accomplished from last section
  • Very useful to do this now way before the due date for the final project!

• Become familiar with rosbag and its commands
  • A very useful post-hoc debugging tool!
rosbags

• Say you’re running your robot and something goes wrong
  • E.g. The velocity is always 5 cm/s slower than you expected
• How could you record data during running and analyze it later?
• rosbag
• rosbags are so named because they are “bags” of ROS data
• This tool allows you to record live data coming in during operation for later playback
Section 6

• Focuses on getting you caught up from last section
• Introduces you to rosbag, a useful post-hoc debugging and analysis tool.